10/20/2022

1. Read Jude’s rewriting of the summaries
2. Try to troubleshoot library installation error on VScode
3. Report findings to Jude

Context:

*Last session, we decided that the control algorithm we will implement is “High-Frequency Nonlinear MPC”*

Goals

1. Finish implementation of 2R Robot

Solve FK and IK equations

­Create 2R Class

Write Tests and Documentation

Using Pytest

Using Doctest

1. Integrate the libraries that will be used to implement the paper into the simulation environment